

THE ACTOR MODEL APPLIED TO THE RASPBERRY PI AND THE EMBEDDED DOMAIN

Omer Kilic || @OmerK
Erlang Solutions Ltd.

Agenda

- Current state of Embedded Systems
- Overview of the Actor Model
- Erlang Embedded Project
- Modelling and developing systems using Erlang
- Experiments with the Raspberry Pi
- Future Explorations
- Q & A

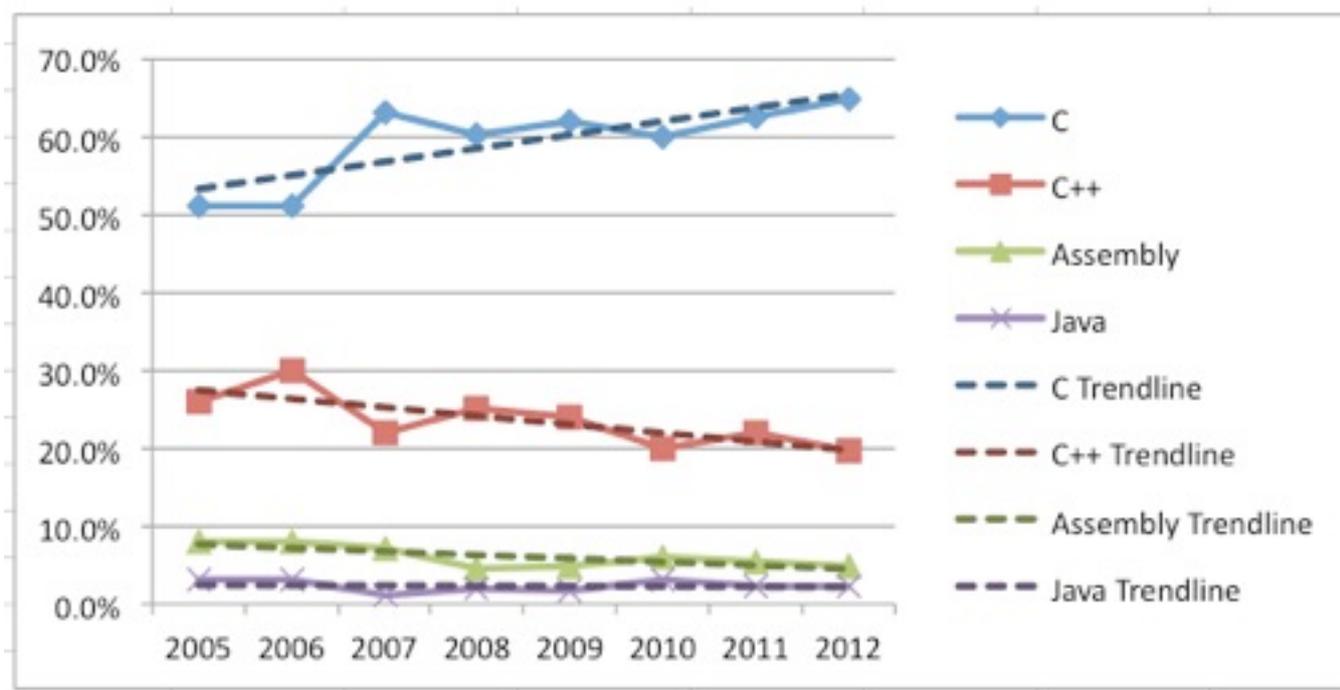
Embedded Systems

“ An embedded system is a computer system designed for specific control functions within a larger system, often with real-time computing constraints. It is embedded as part of a complete device often including hardware and mechanical parts. By contrast, a general-purpose computer, such as a personal computer (PC), is designed to be flexible and to meet a wide range of end-user needs

– Infinite Wisdom of Wikipedia

#include "stats.h"

The four languages most often reported as the primary language for embedded projects for the years 2005 to 2012, along with linear trendlines.



Source: <http://embedded.com/electronics-blogs/programming-pointers/4372180/Unexpected-trends>

Current Challenges

- Complex SoC platforms
- “Internet of Things”
 - Connected and distributed systems
- Multicore and/or heterogeneous devices
- Time to market constraints

Embedded Systems

- Bare Metal
 - No underlying OS or high level abstractions
- RTOS
 - Minimal interrupt and thread switching latency, scheduling guarantees, minimal jitter
- Embedded Linux
 - Slimmed down Linux, with hardware interfaces

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RTOS Concepts

- Notion of "tasks"
- OS-supervised interprocess messaging
 - Shared memory
- Mutexes/Semaphores/Locks
- Scheduling
 - Pre-emptive: event driven
 - Round-robin: time multiplexed

Embedded Linux

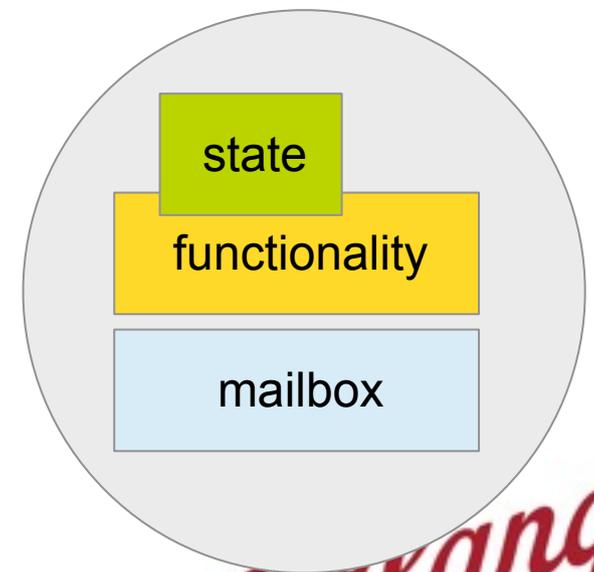
- Not a new concept, increased popularity due to abundant supply of cheap boards
 - Raspberry Pi, Beagleboard/Beaglebone, Gumstix et al.
- Familiar set of tools for software developers, new territory for embedded engineers
 - No direct mapping for RTOS concepts, especially tasks
- Complex device driver framework
 - Here be dragons

Actor Model

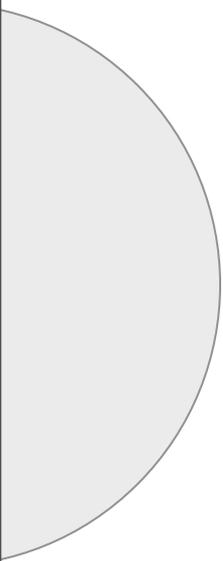
- Proposed in 1973 by Hewitt, Bishop, and Steiger
 - “Universal primitives of concurrent computation”
- Building blocks for modular, distributed and concurrent systems
- No shared-state, self-contained and atomic
- Implemented in a variety of programming languages

Actor Model

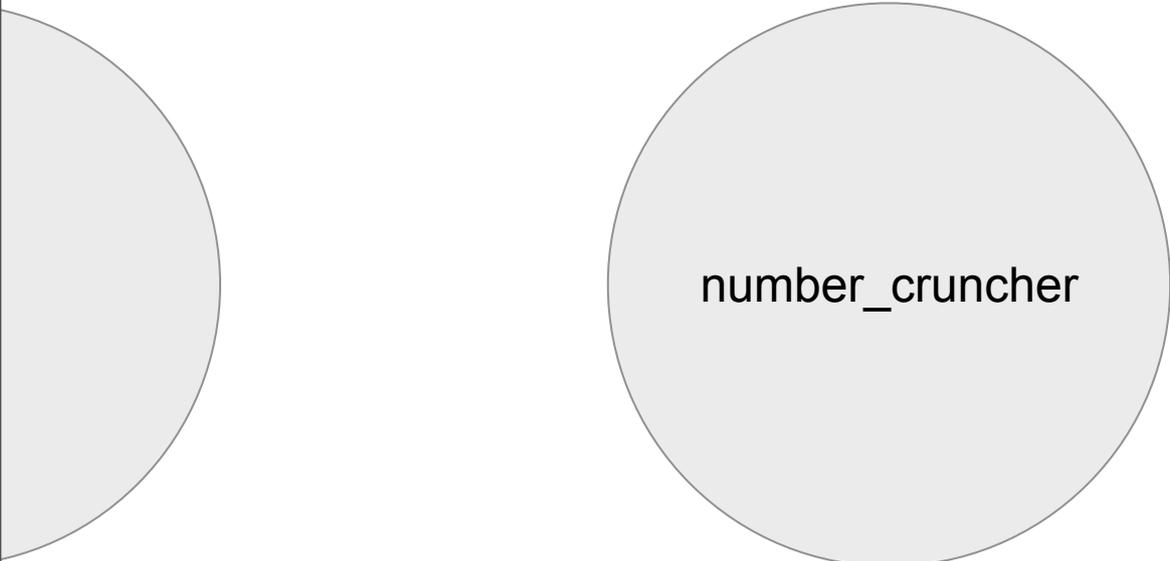
- Asynchronous message passing
 - Messages kept in a mailbox and processes in the order they are received in
- Upon receiving a message, actors can:
 - Make local decisions and change internal state
 - Spawn new actors
 - Send messages to other actors



Actor Model

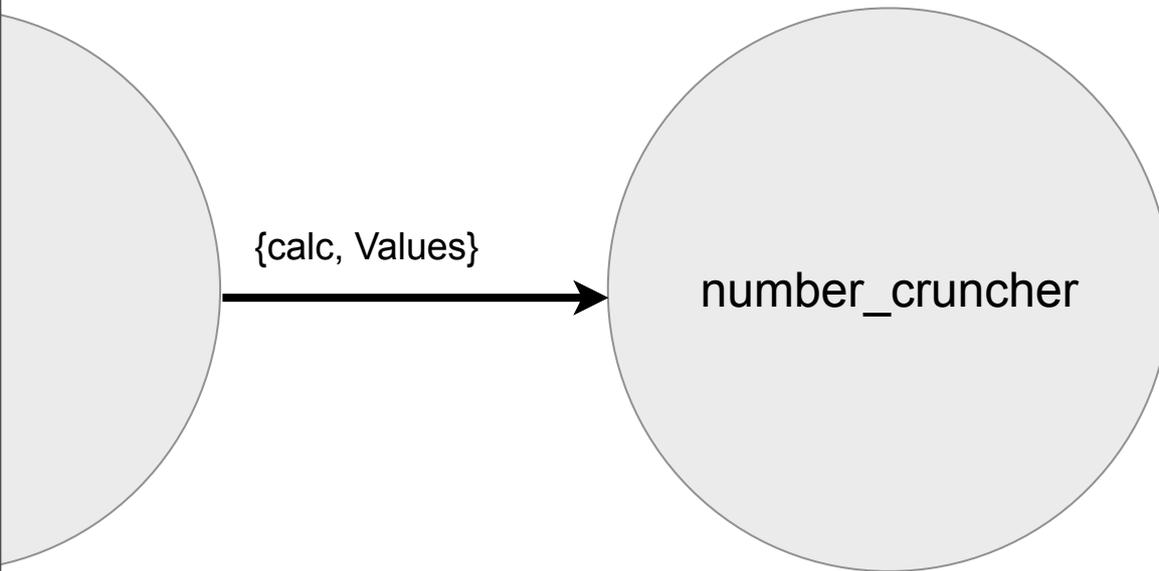


Actor Model

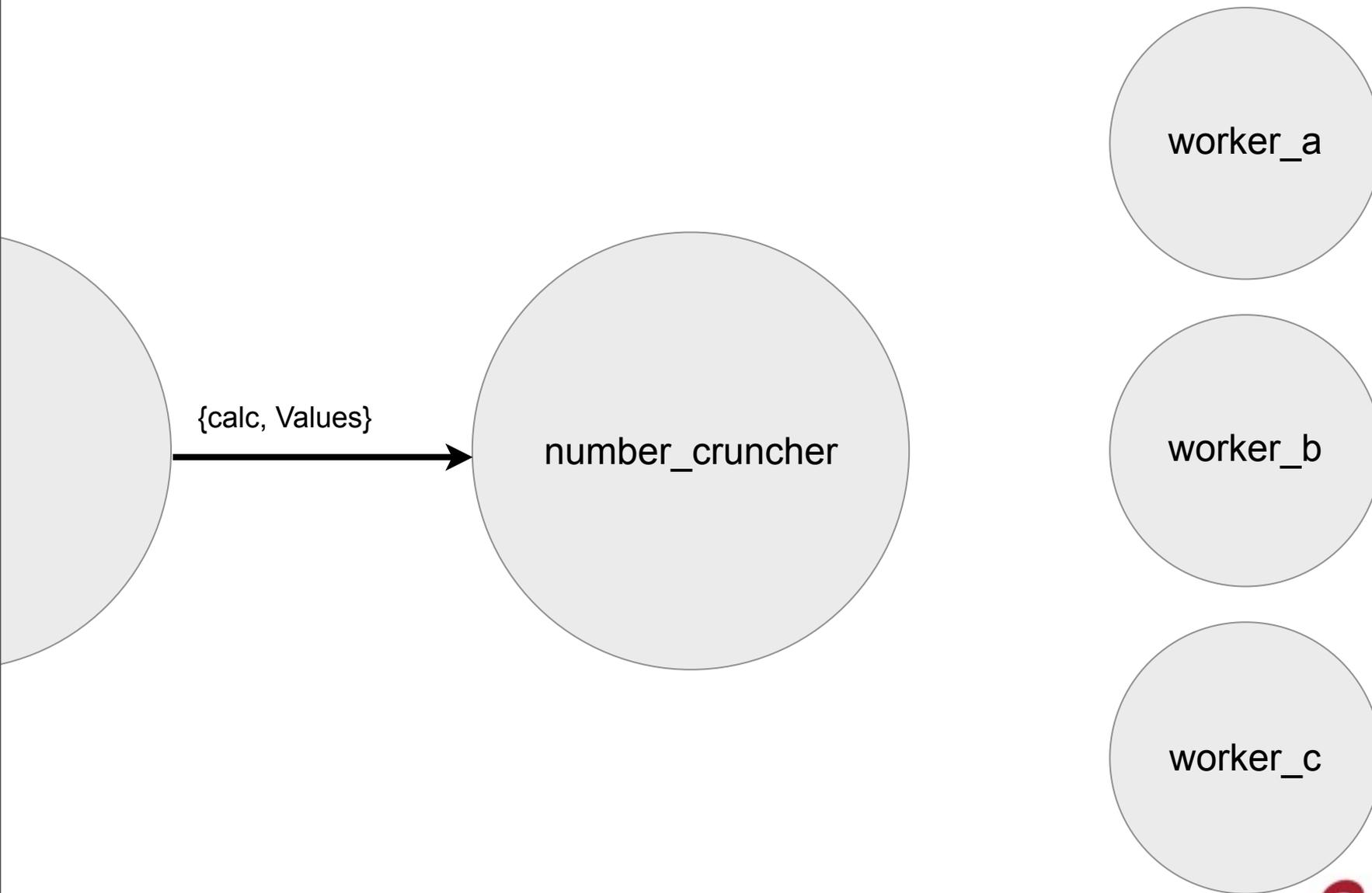


number_cruncher

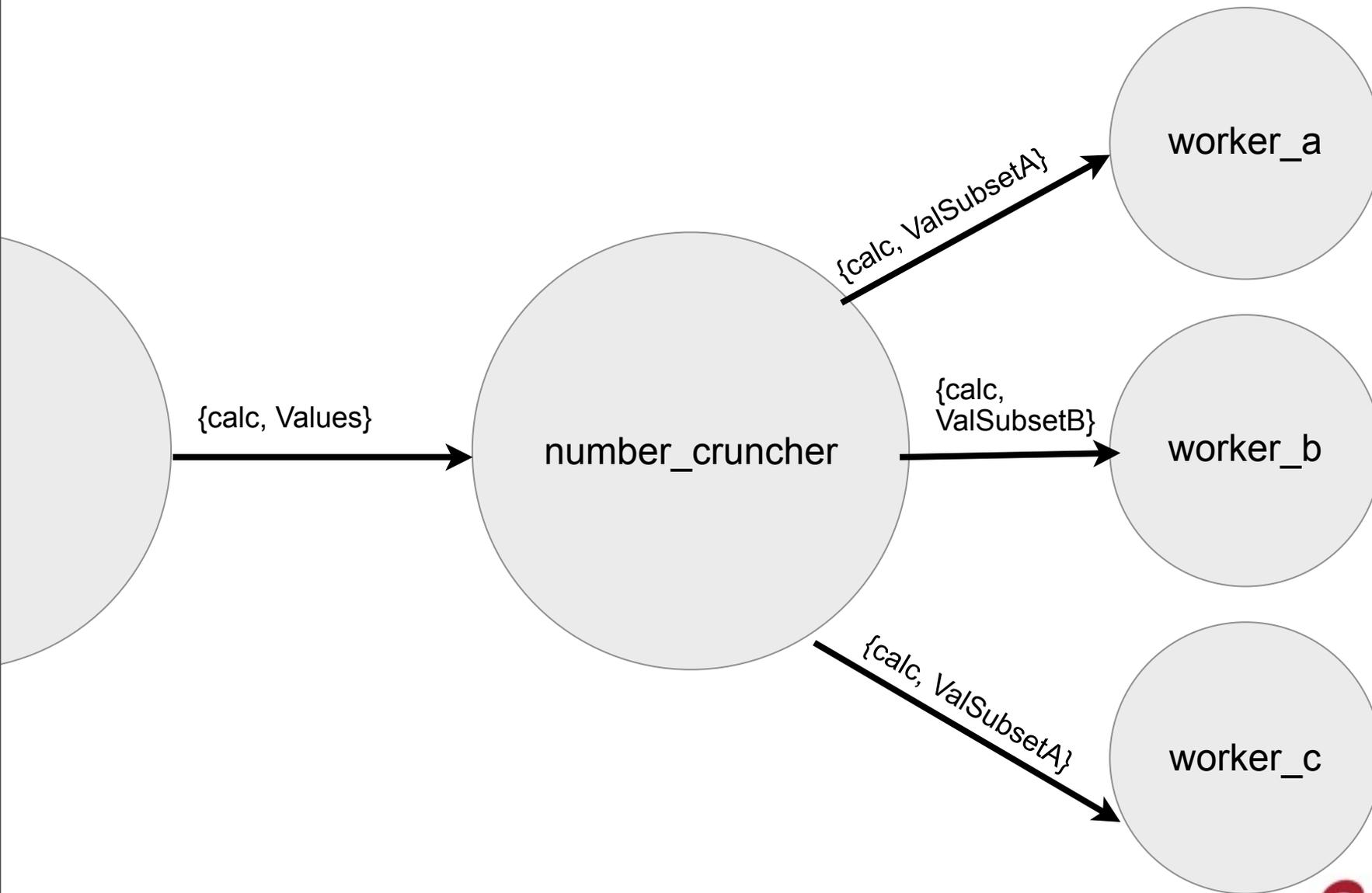
Actor Model



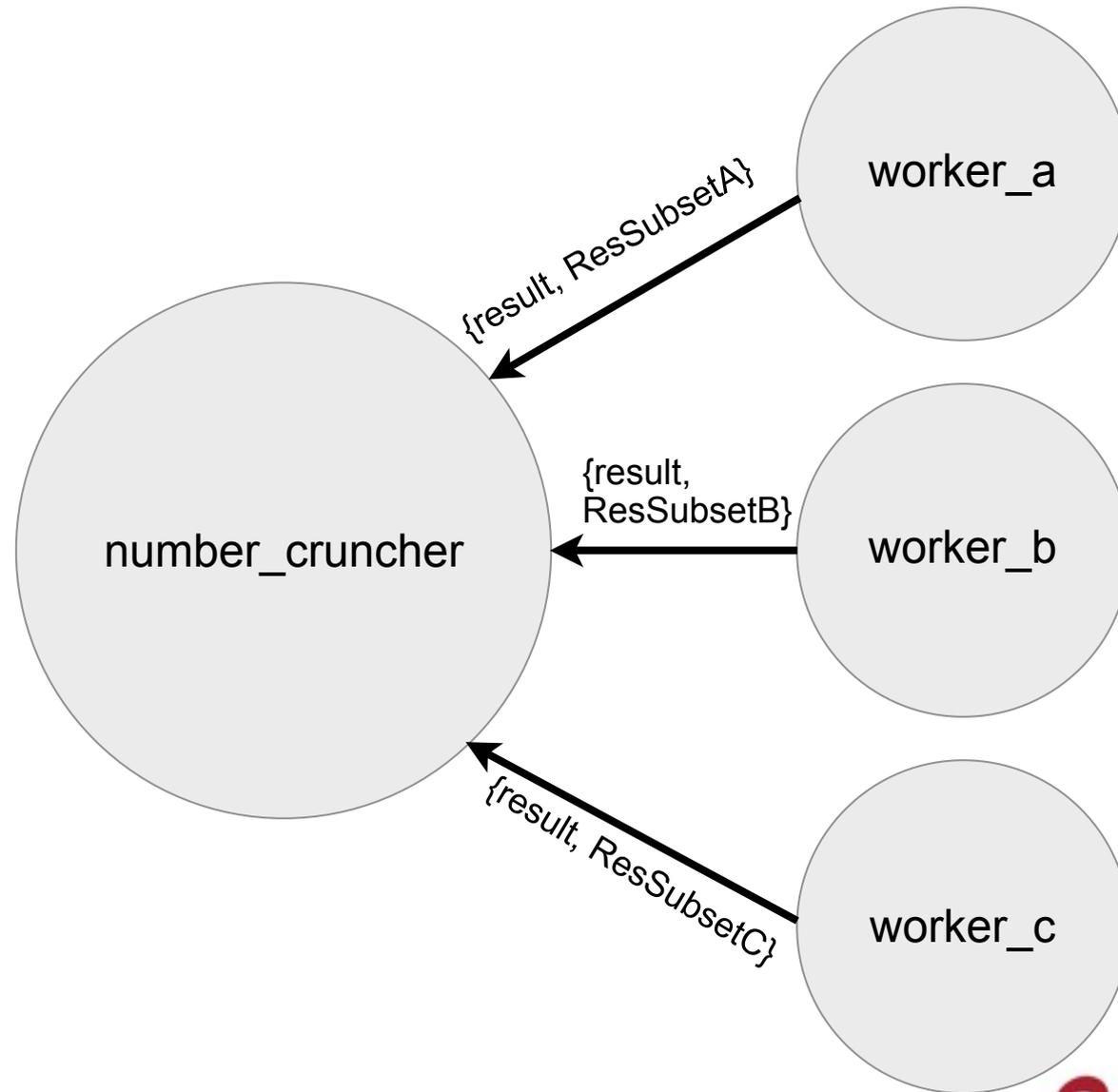
Actor Model



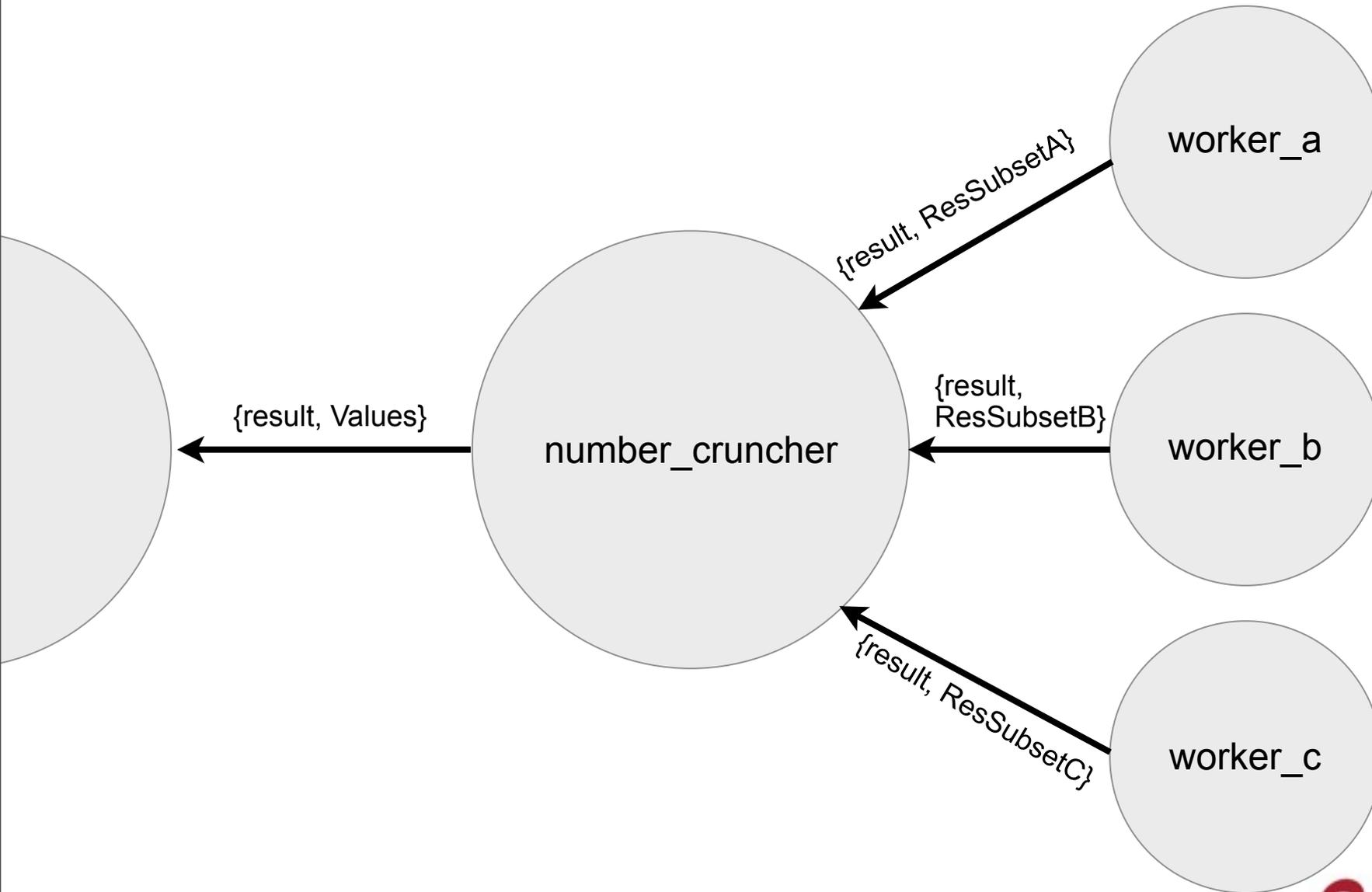
Actor Model



Actor Model



Actor Model



Limitations of the Actor Model

- No notion of inheritance or general hierarchy
 - Specific to the language and library implementation
- Asynchronous message passing can be problematic for certain applications
 - Ordering of messages received from multiple processes
- Abstract definition may lead to inconsistency in larger systems
 - Fine/Coarse Grain

Erlang Embedded

- Knowledge Transfer Partnership between Erlang Solutions and University of Kent
 - Aim of the project: Bring the benefits of concurrent systems development using Erlang to the field of embedded systems; through investigation, analysis, software development and evaluation.
- <http://erlang-embedded.com>

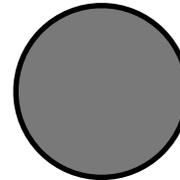
Why Erlang

- Implements the Actor model
- Battle-tested at Ericsson and many other companies
 - Originally designed for embedded applications
- Support for concurrency and distributed systems out of the box
- Easy to create robust systems
- (...and more!)

High Availability / Reliability

- Simple and consistent error recovery and supervision hierarchies
- Built in fault-tolerance
 - Isolation of Actors
- Support for dynamic reconfiguration
 - Hot code loading

Creating an Actor

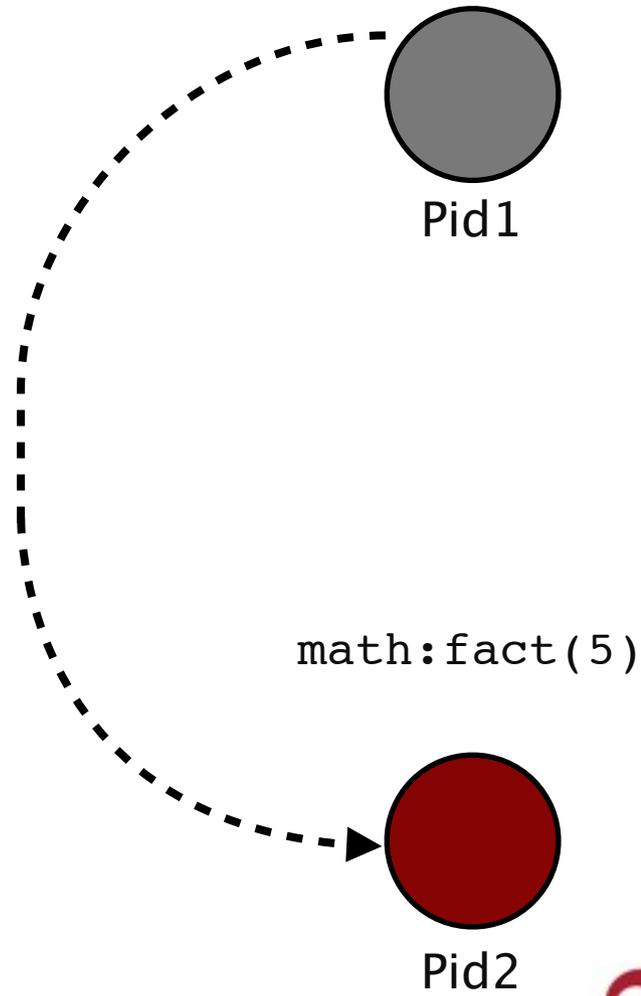


Pid1

```
spawn(math, fact, [5])
```

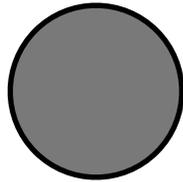
Creating an Actor

```
spawn(math, fact, [5])
```

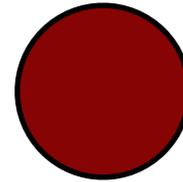


Communication

Pid1

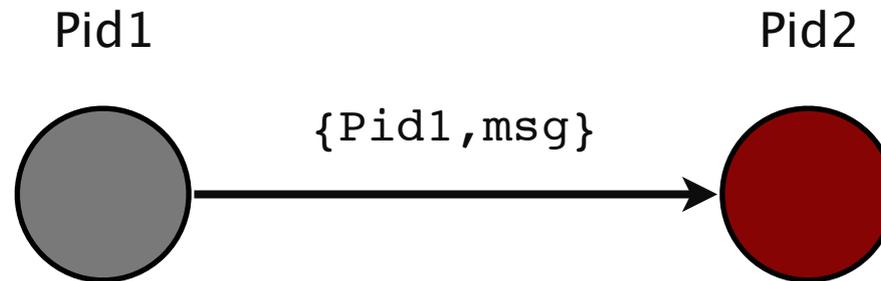


Pid2



```
Pid2 ! {self(),msg}
```

Communication

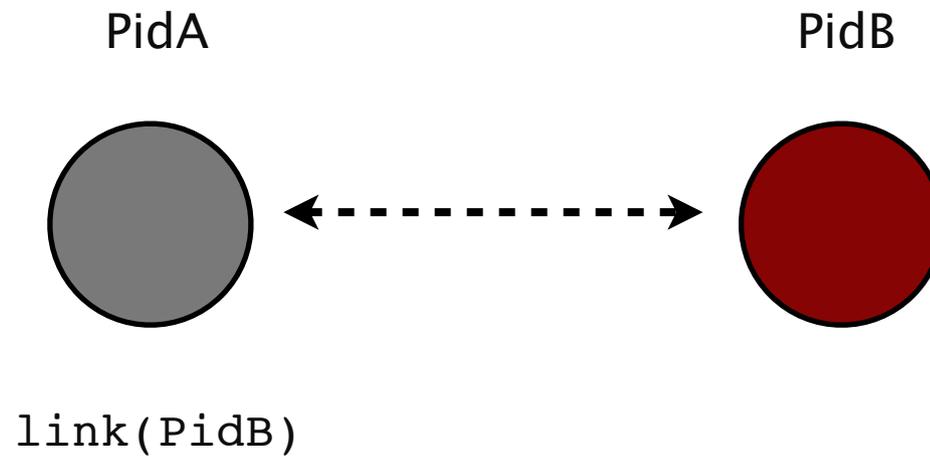


Pid2 ! {self(),msg}

Bidirectional Links

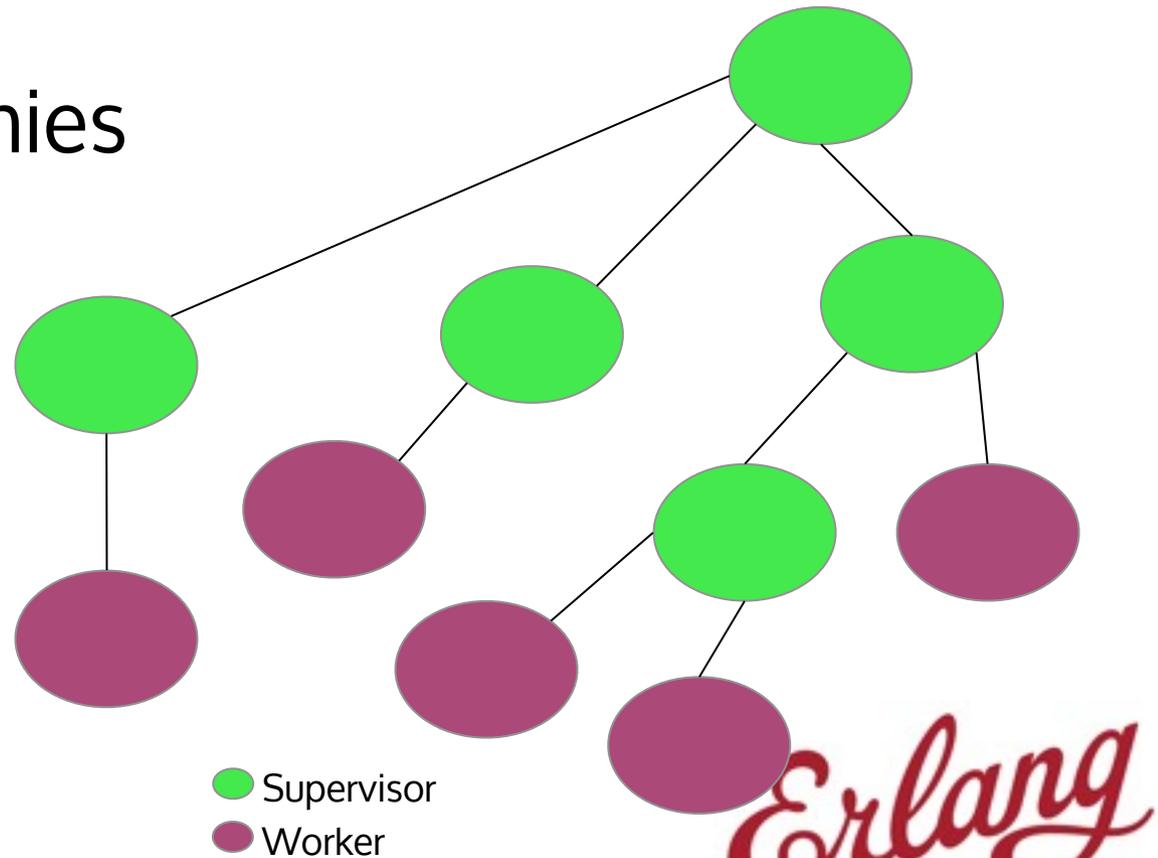


Bidirectional Links

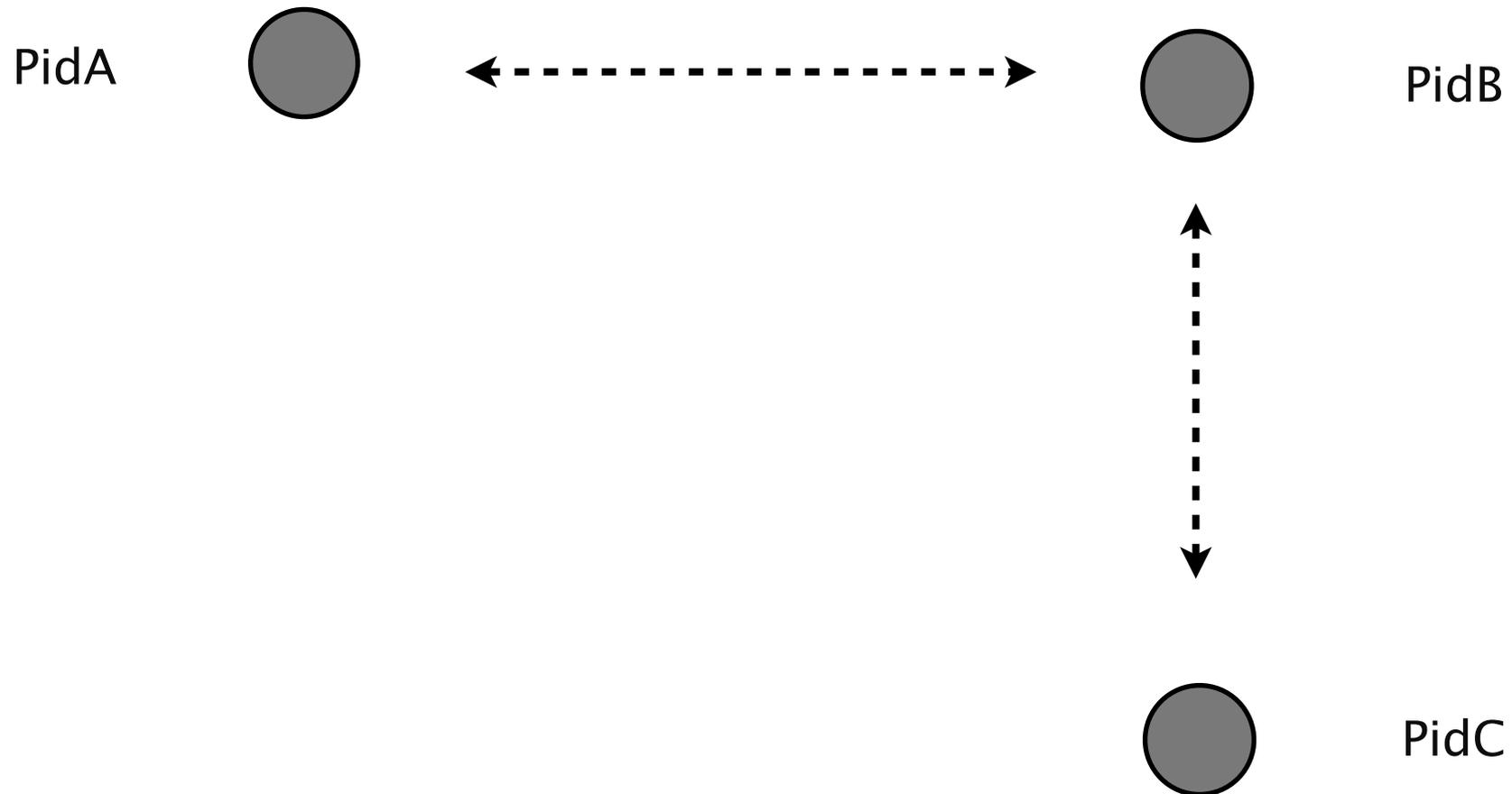


Process Error Handling

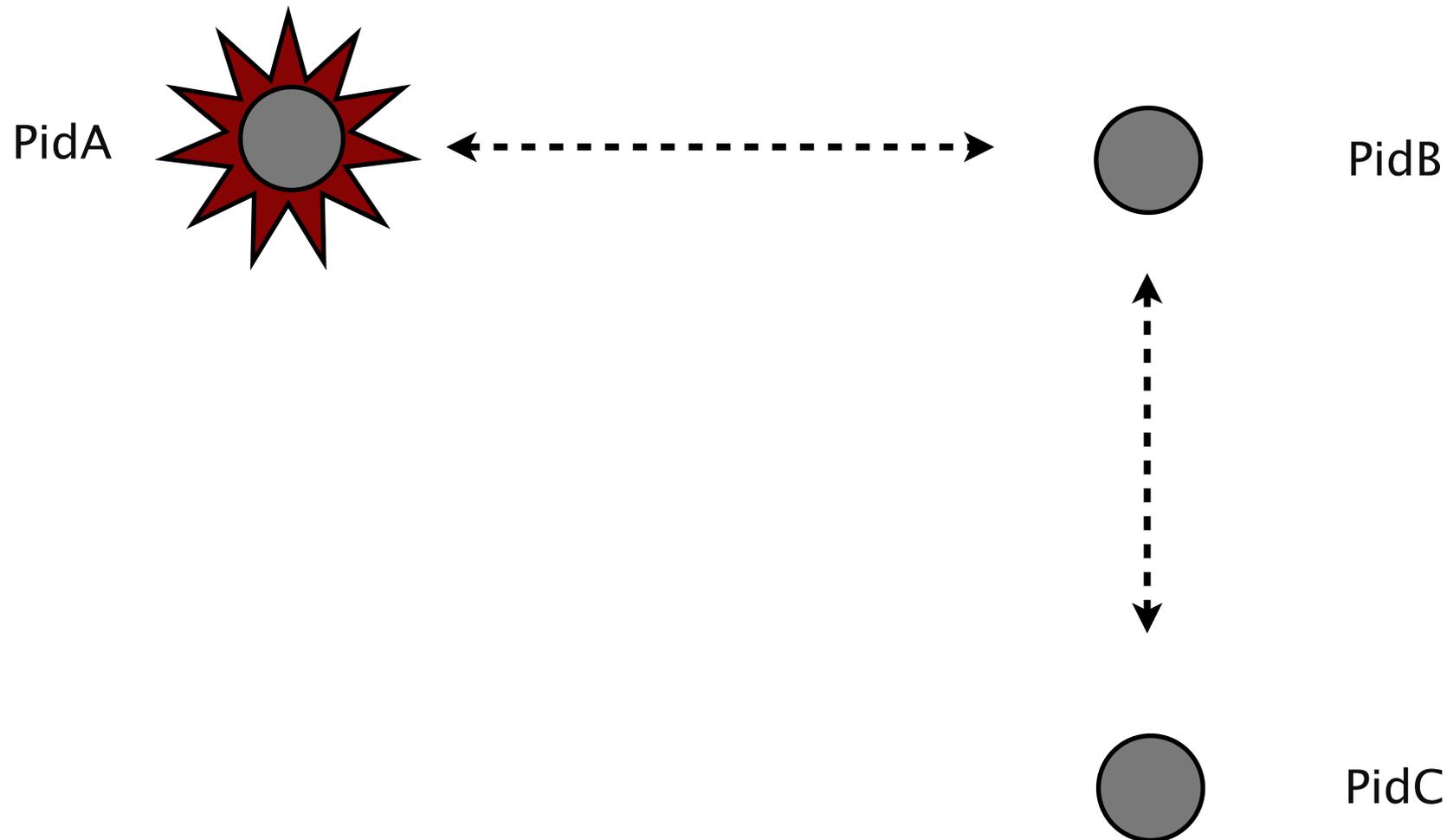
- Let it Fail!
 - Abstract error handling away from the modules
 - Leaner modules
- Supervision hierarchies



Propagating Exit Signals

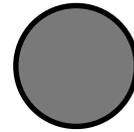


Propagating Exit Signals

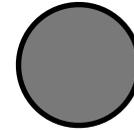


Propagating Exit Signals

`{'EXIT', PidA, Reason}`

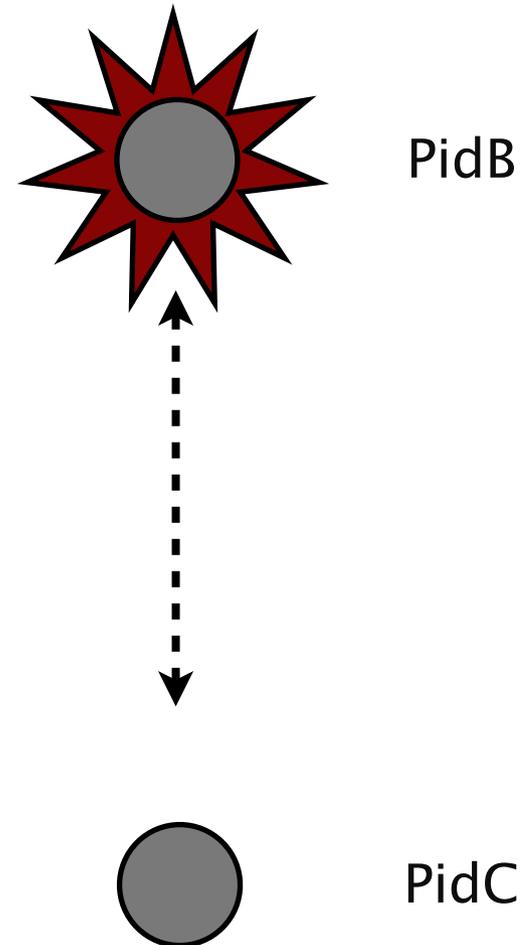


PidB



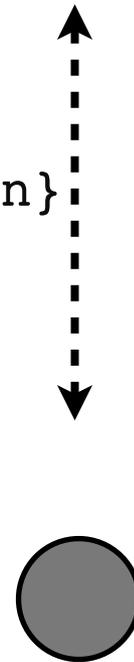
PidC

Propagating Exit Signals



Propagating Exit Signals

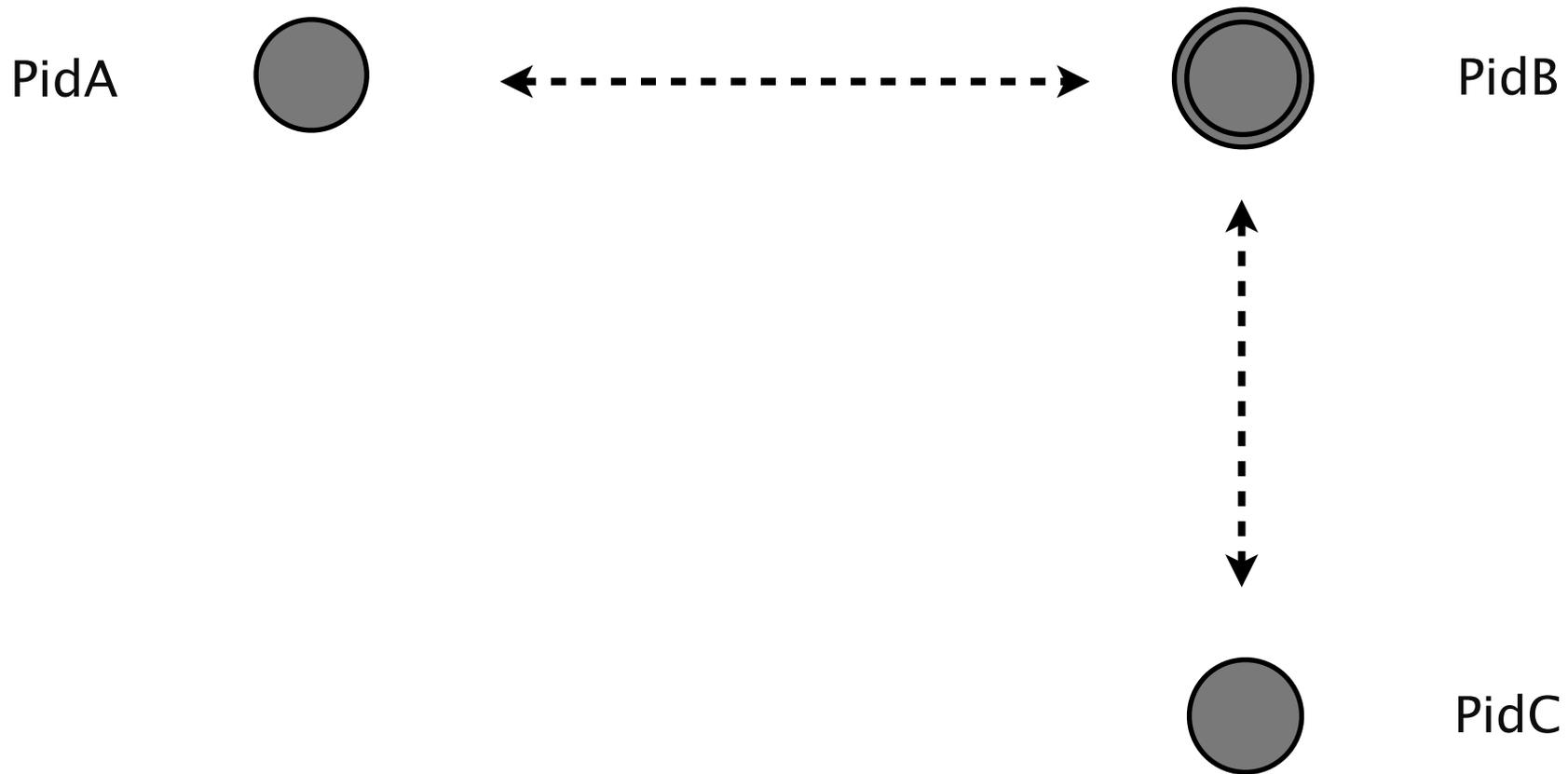
`{ 'EXIT', PidB, Reason }`



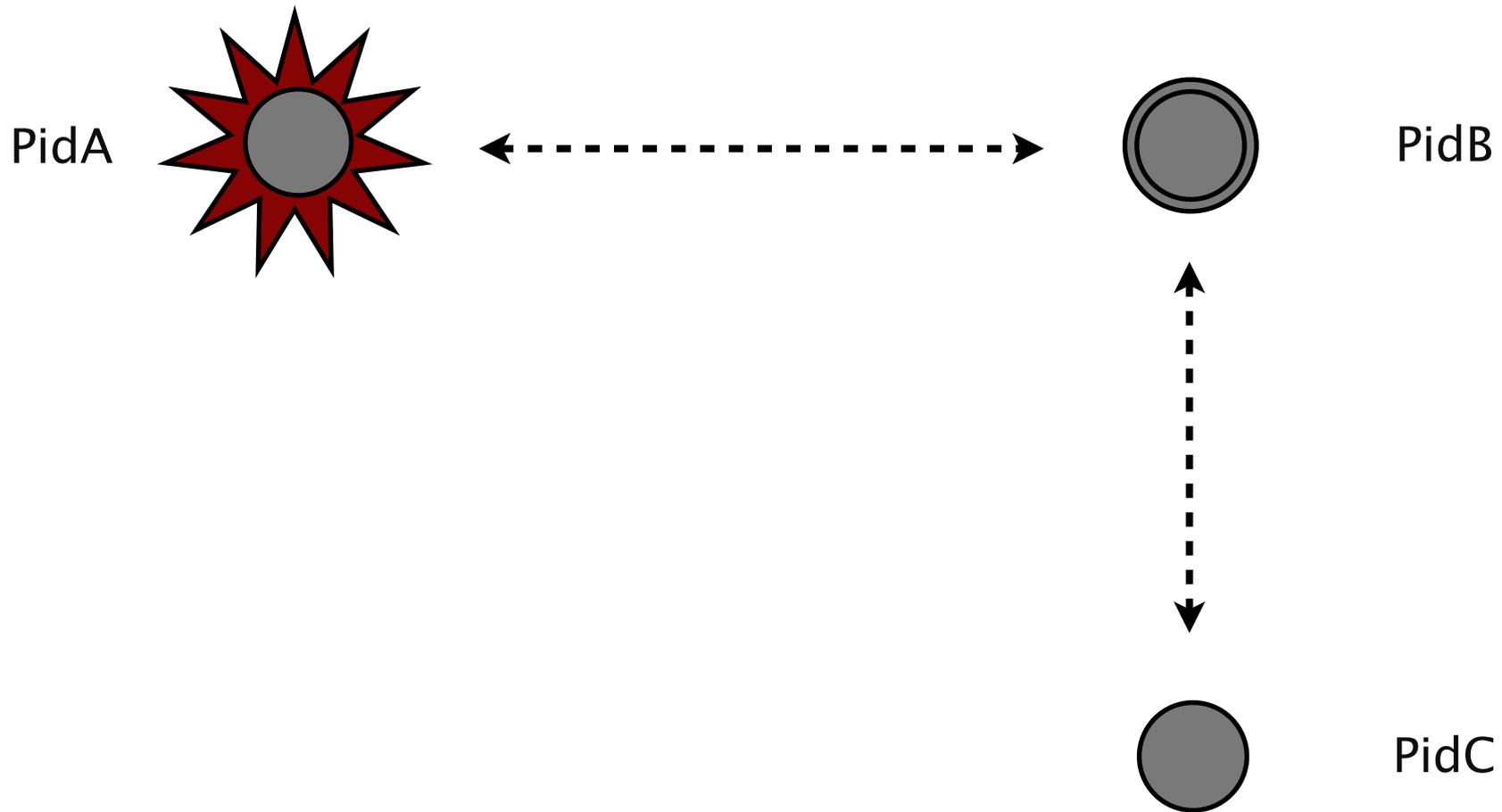
PidC

Propagating Exit Signals

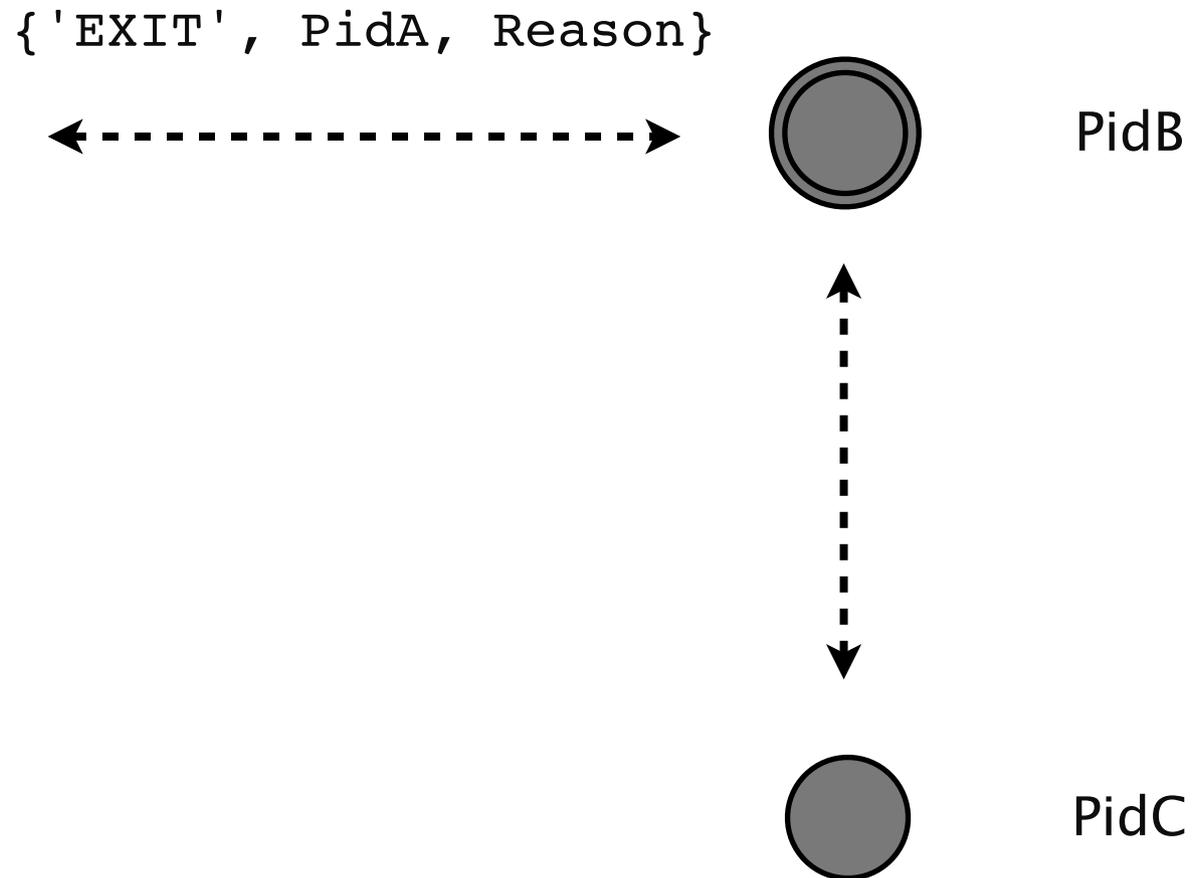
Trapping Exits



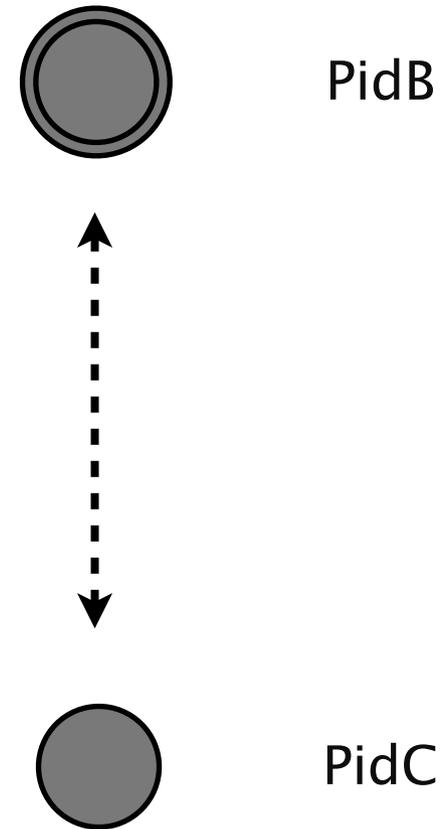
Trapping Exits



Trapping Exits

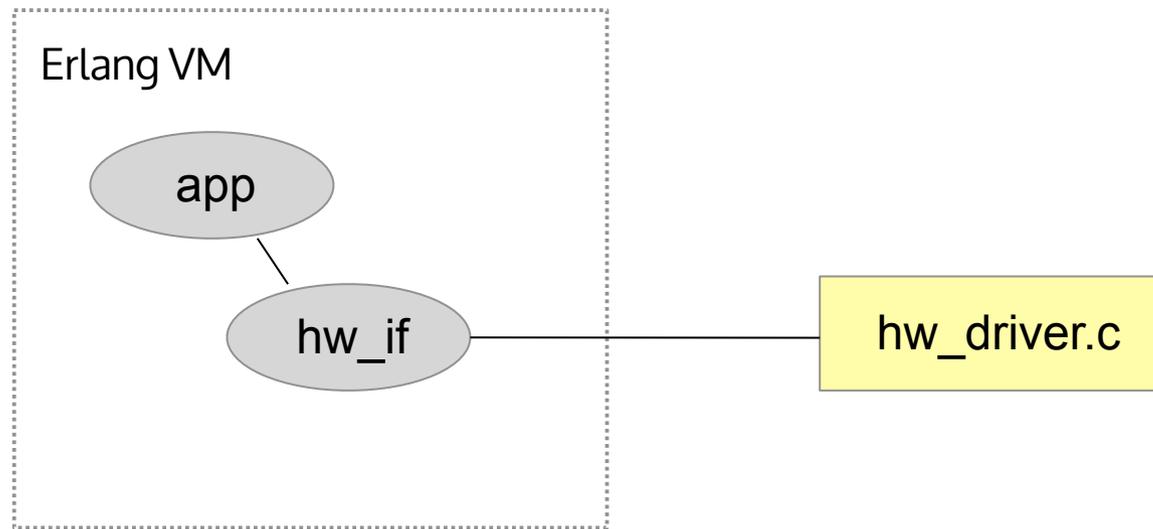


Trapping Exits



External Interfaces

- Native Implemented Functions (NIFs) and ports used to interface external world to the Erlang runtime.



Erlang, the Maestro



[\(flickr/dereckesanches\)](https://www.flickr.com/photos/dereckesanches/)

Raspberry Pi

- 700 MHz ARM11
- 256 MB DDR2 RAM
- 10/100Mb Ethernet
- 2x USB 2.0
- (HDMI, Composite Video, 3.5mm Stereo Jack, DSI, CSI-2)



\$35

Raspberry Pi in Education



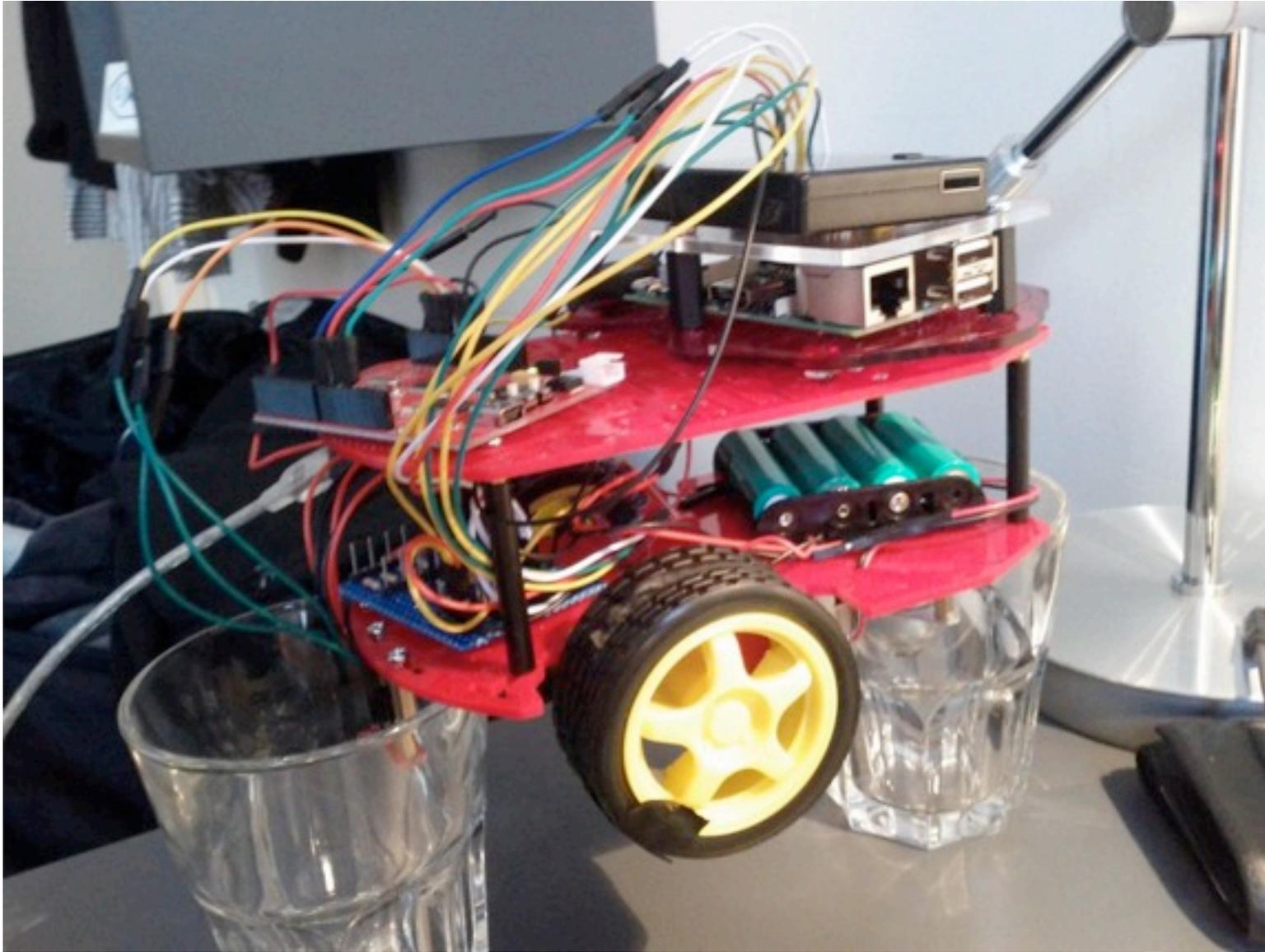
[\(flickr/lebeus\)](#)

- The Raspberry Pi Foundation is a UK registered charity.
- Mission statement: "...to promote the study of computer science and related topics, especially at school level, and to put the fun back into learning computing."
- Future Engineers/Programmers!

Raspberry Pi Peripherals

- GPIO
- UART
- I2C
- I2S
- SPI
- PWM
- DSI
- CSI-2

The ErlBuggy!

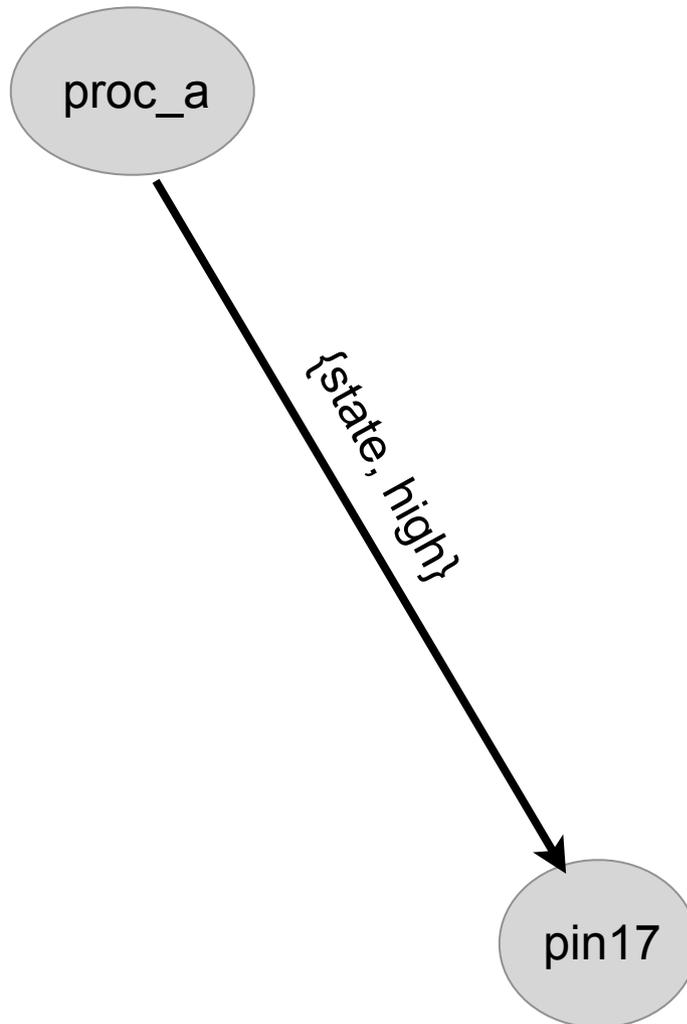


ErlBuggy

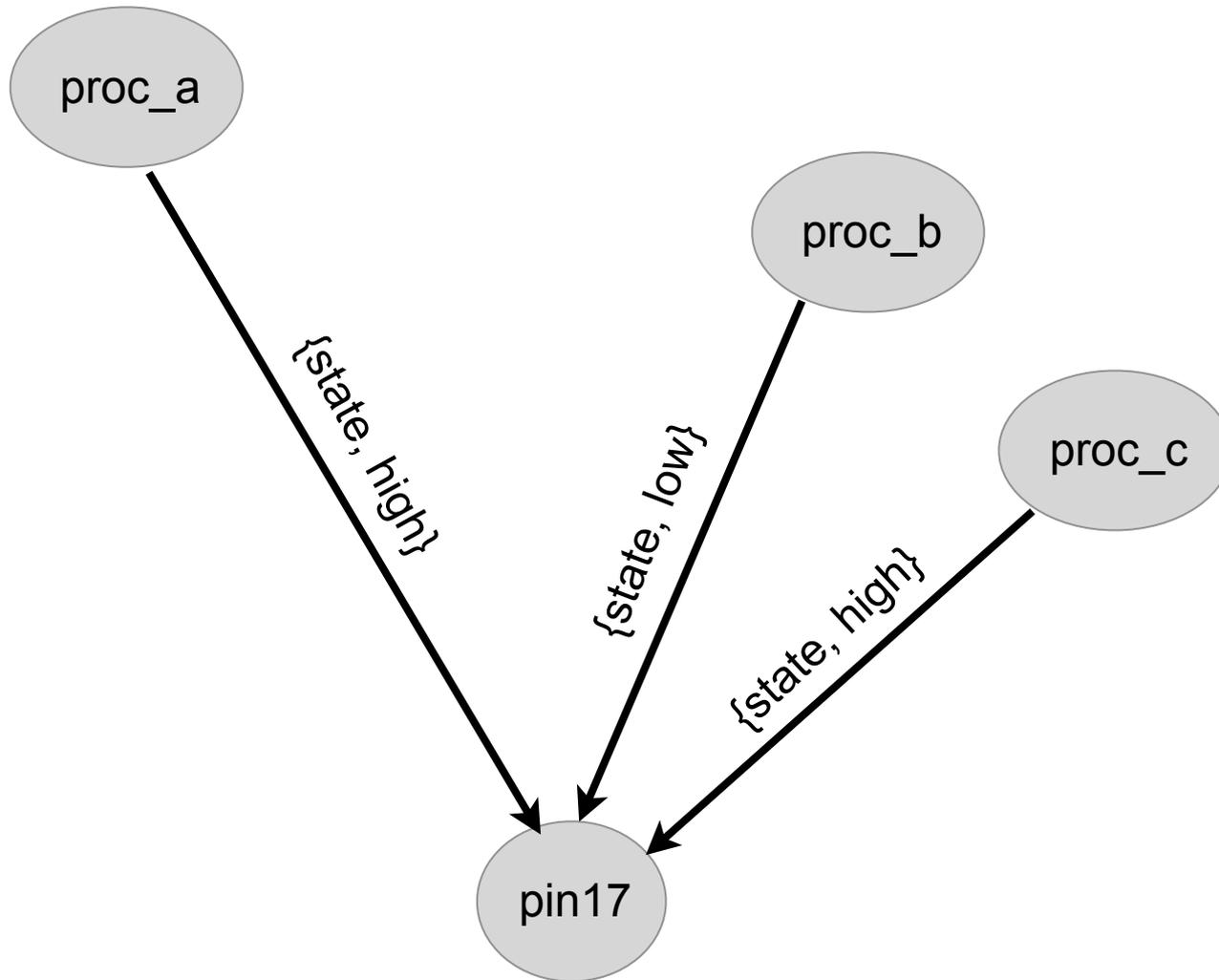


<http://vimeo.com/48375416>

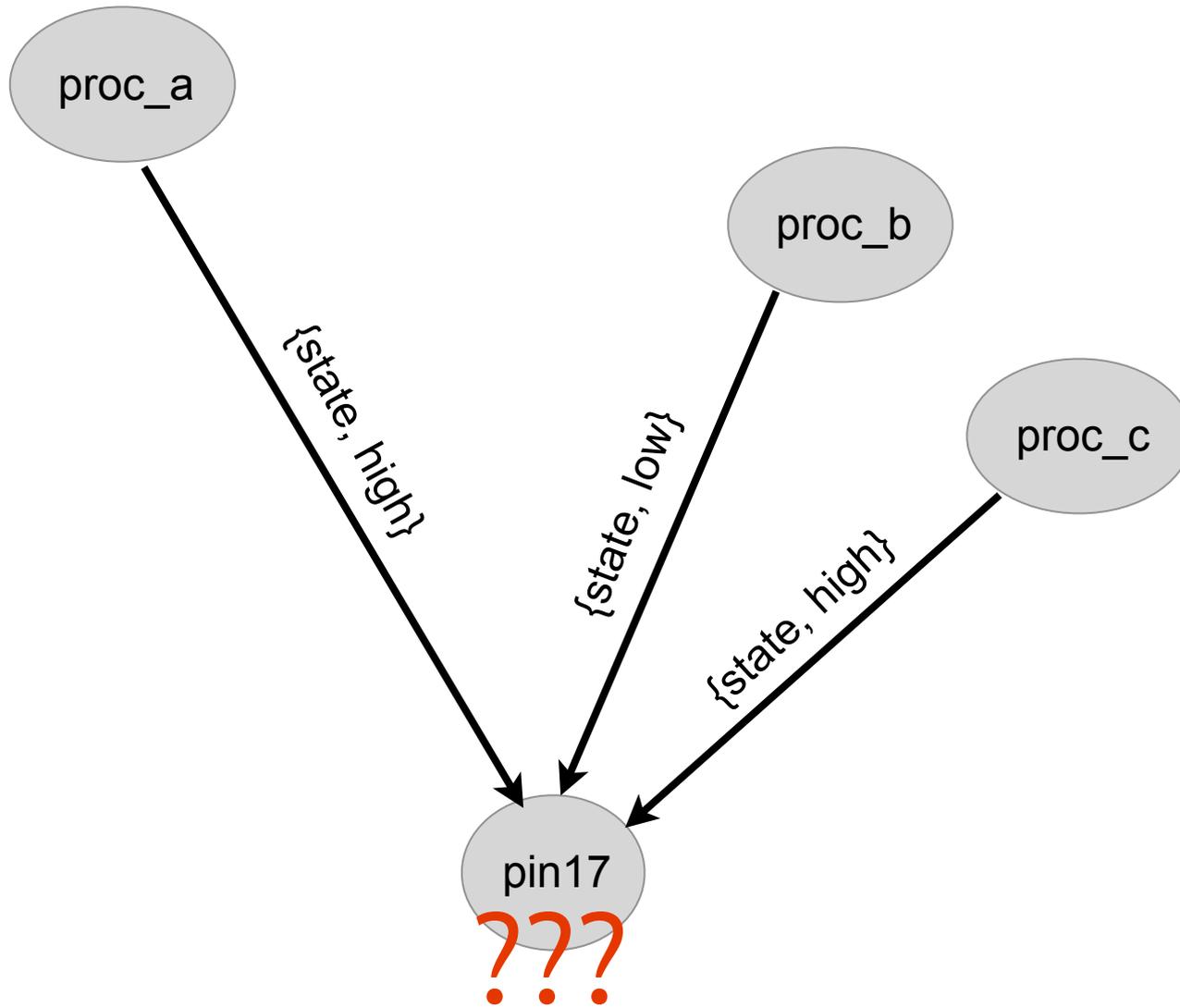
Example: GPIO



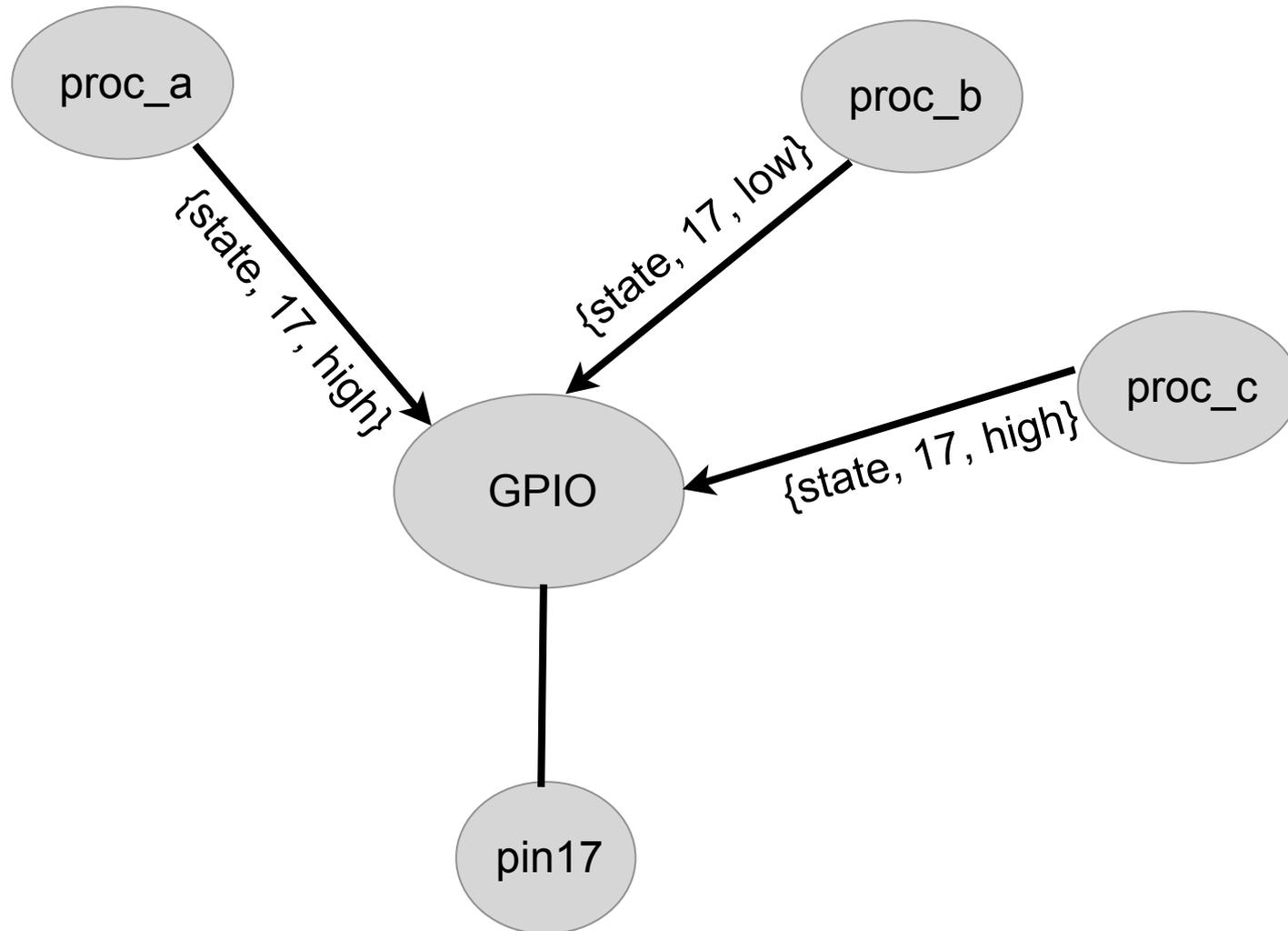
Example: GPIO



Example: GPIO



Example: GPIO



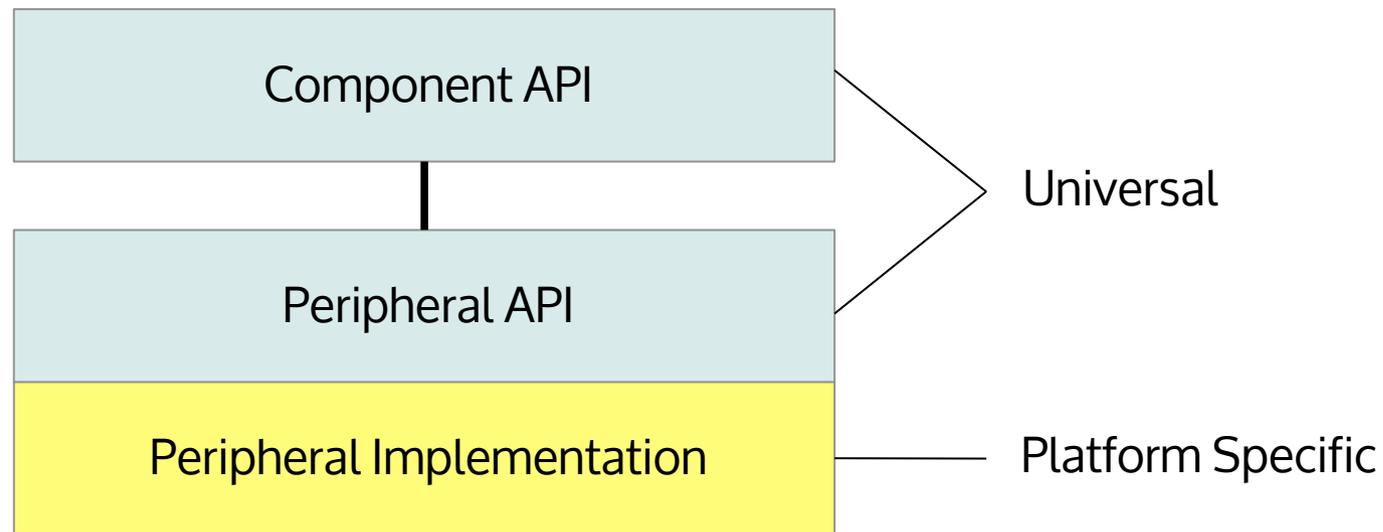
GPIO Proxy

- Replaces 'locks' in traditional sense of embedded design
 - Access control/mutual exclusion
- Can be used to implement safety constraints
 - Toggling rate, sequence detection, direction control, etc.

Fine Grain Abstraction

- Advantages
 - Application code becomes simpler
 - Concise and shorter modules
 - Testing becomes easier
 - Code re-use (potentially) increases
- Disadvantage
 - Architecting fine grain systems is difficult

Universal Peripheral/Component Modules

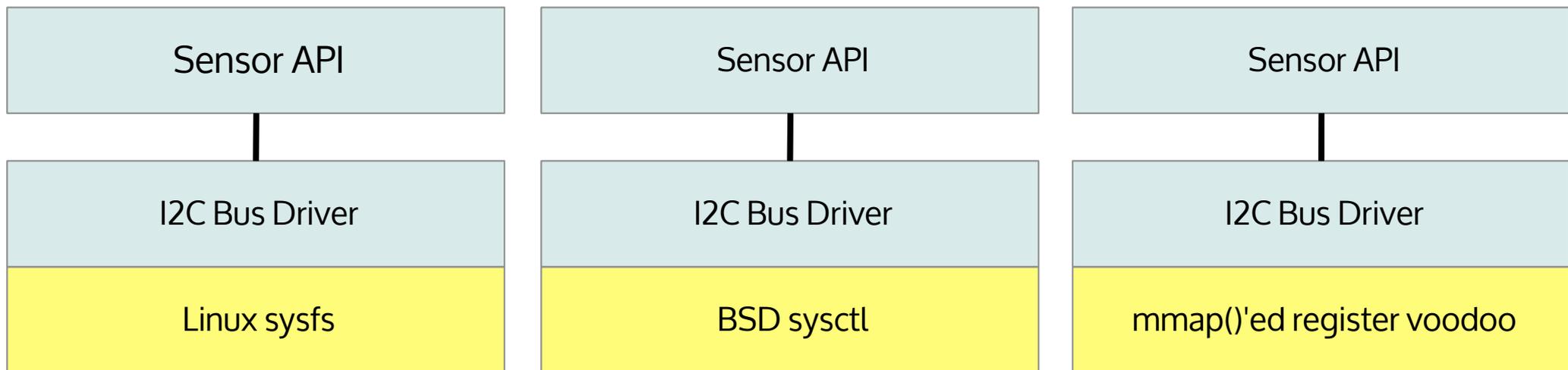


Universal Peripheral/Component Modules

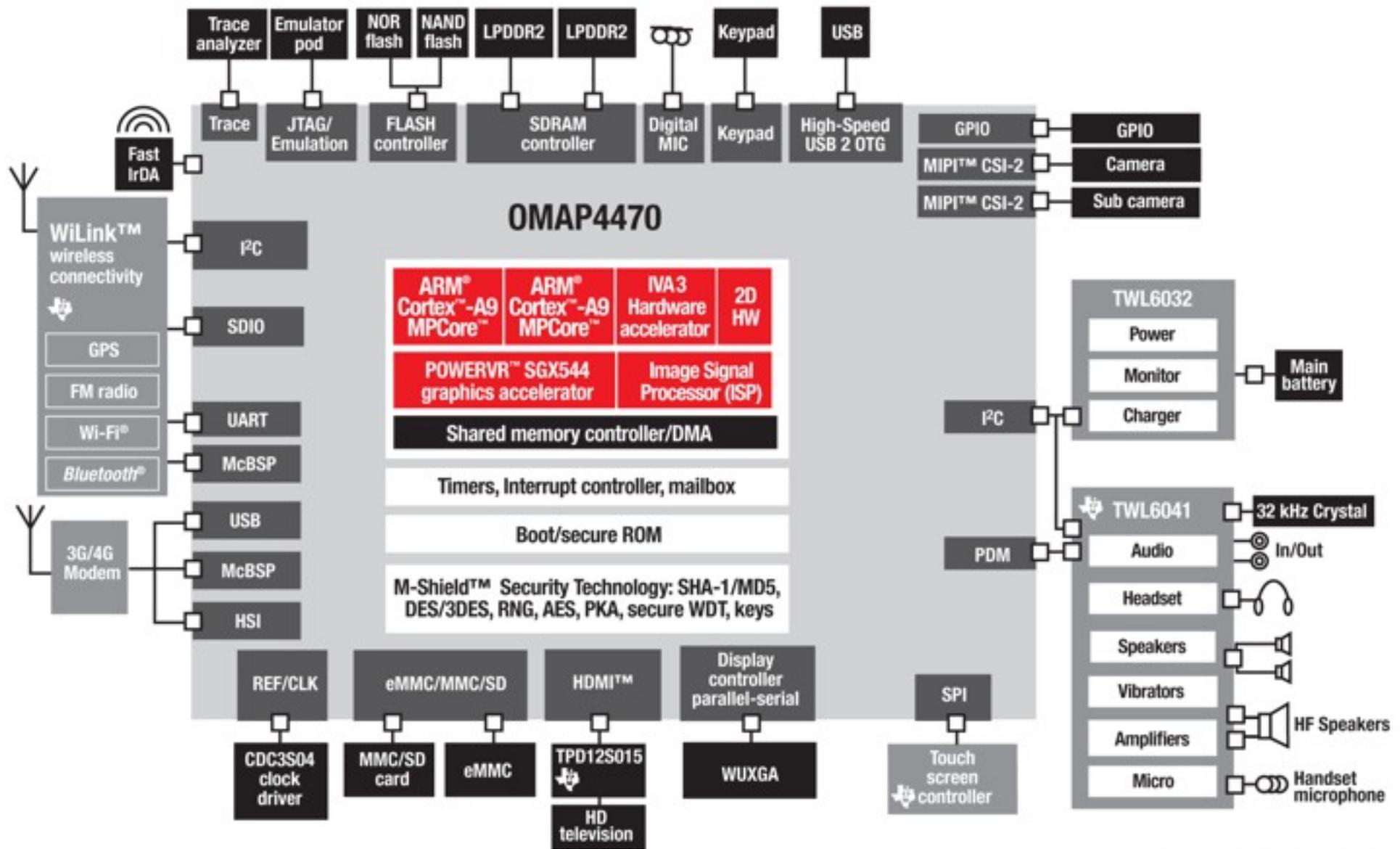
An Example:



Temperature Sensor with I2C Interface



TI OMAP Reference System

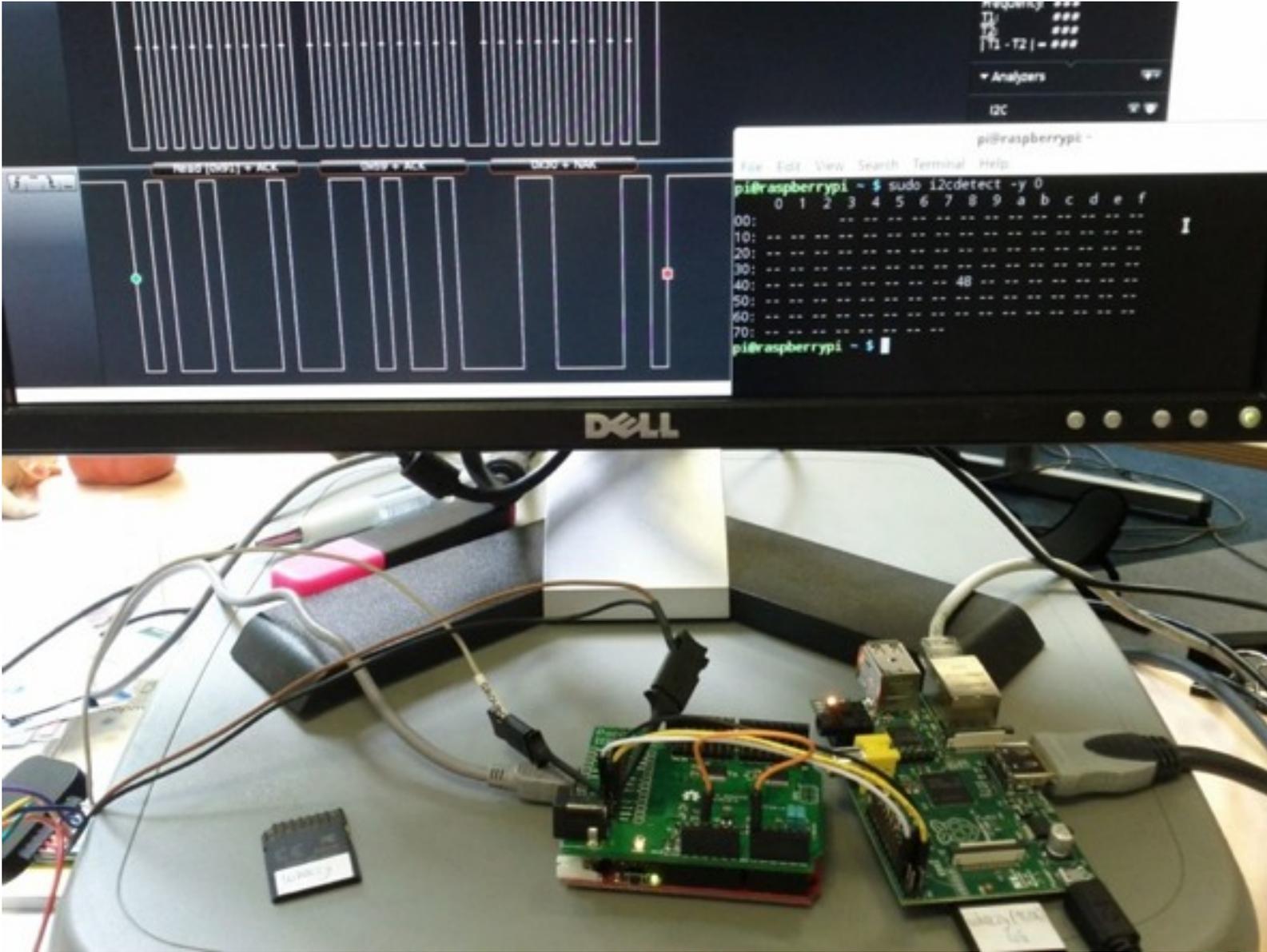


Ponte Prototype

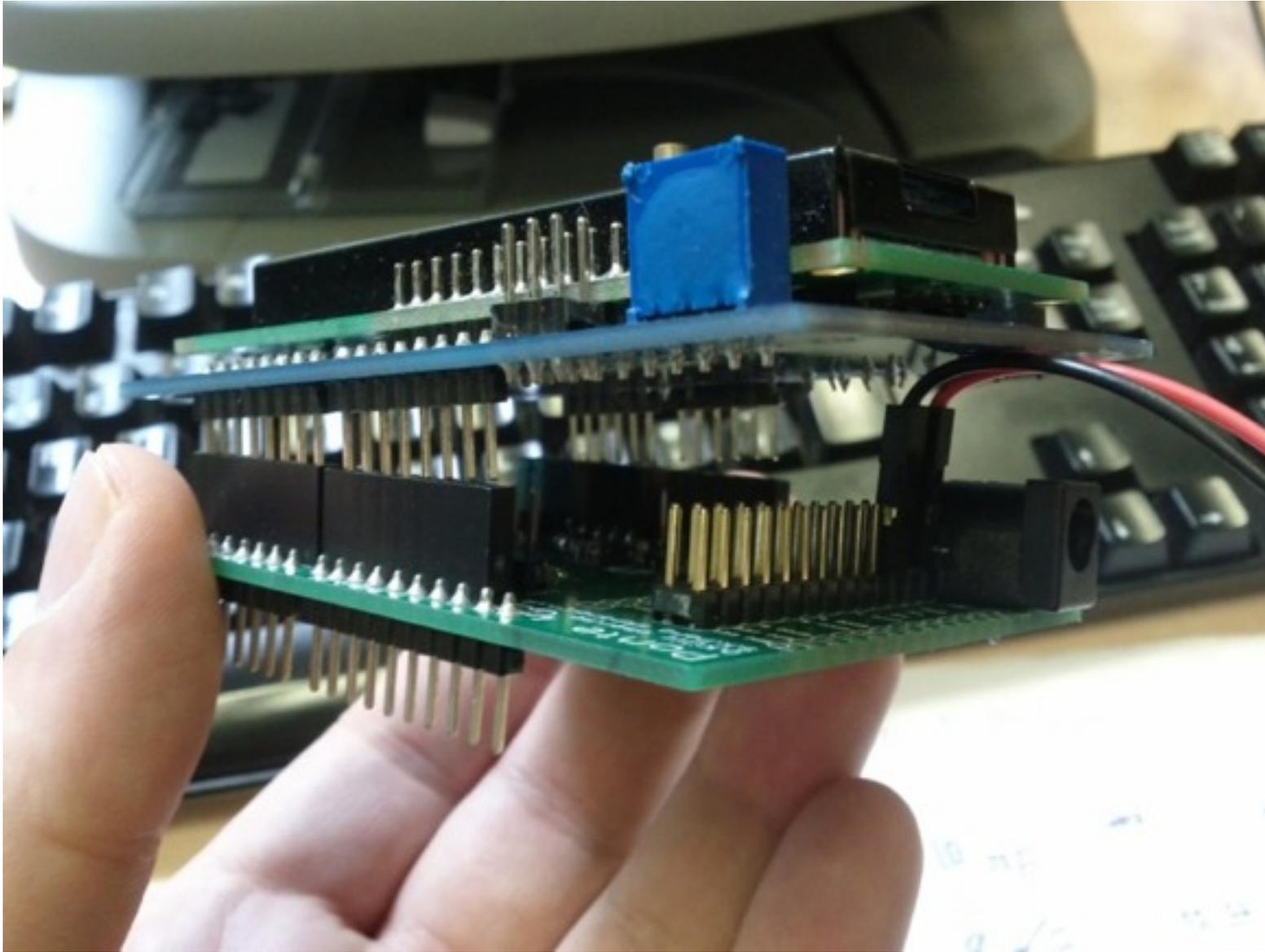


[\(flickr/carrierdetect\)](https://www.flickr.com/photos/carrierdetect/)

Ponte Prototype



Ponte Prototype



Hardware Simulator (WIP)

The image shows a screenshot of the Erlang Hardware Simulator GUI and its associated terminal output. The GUI, titled "Erlang Hardware Simulator", displays a virtual "Erlang Embedded Demo Board" with various components:

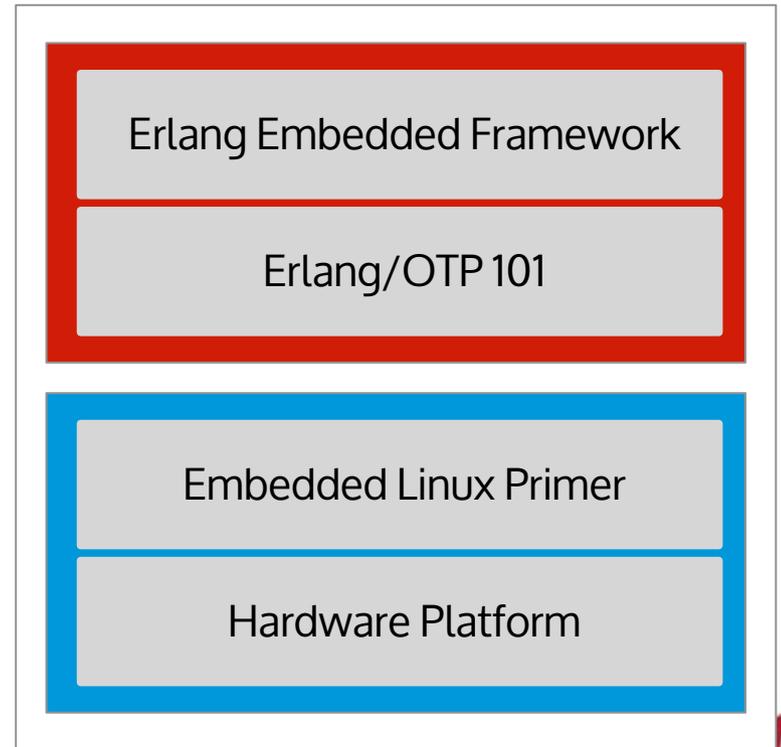
- PWM LED:** A blue LED and a black component labeled "P3002".
- GPIO LEDs:** Three LEDs, one of which is red.
- GPIO Pushbuttons:** Three pushbutton components.
- MCP23008 LEDs:** Four LEDs.
- MCP23008 Switches:** Four switches, all labeled "ON".
- MCP3002 ADC Components:** A potentiometer showing a value of 1.03 V and a temperature sensor showing a value of 70 °C.

The terminal window on the left shows network traffic and message exchanges, including:

```
1. beam.smp
short text msg: len=8, Masks=2424610658, Payload=<<
received: text message with len:8 - <<"tmp36 49">>
tcp received <<129,136,102,188,130,75,18,209,242,12
short text msg: len=8, Masks=1723630155, Payload=<<
received: text message with len:8 - <<"tmp36 55">>
tcp received <<129,136,116,191,102,239,0,210,22,220
short text msg: len=8, Masks=1958700783, Payload=<<
received: text message with len:8 - <<"tmp36 61">>
tcp received <<129,136,212,201,251,20,160,164,139,3
short text msg: len=8, Masks=3570006804, Payload=<<
received: text message with len:8 - <<"tmp36 65">>
tcp received <<129,136,34,118,175,144,86,27,223,163
short text msg: len=8, Masks=578203536, Payload=<<8
received: text message with len:8 - <<"tmp36 66">>
tcp received <<129,136,117,157,240,251,1,240,128,20
short text msg: len=8, Masks=1973285115, Payload=<<
received: text message with len:8 - <<"tmp36 68">>
tcp received <<129,136,151,234,249,188,227,135,137,
short text msg: len=8, Masks=2548758972, Payload=<<
received: text message with len:8 - <<"tmp36 69">>
tcp received <<129,136,204,111,218,161,184,2,170,14
short text msg: len=8, Masks=3429882529, Payload=<<
received: text message with len:8 - <<"tmp36 70">>
tcp received <<129,138,55,48,241,154,94,2,146,197,6
short text msg: len=10, Masks=925954458, Payload=<<
received: text message with len:10 - <<"i2c_sw_2 1
3>
```

Erlang Embedded Training Stack

- A complete package for people interested in developing the next generation of concurrent/distributed Embedded Systems
- Training Modules
 - Embedded Linux Primer
 - Erlang/OTP 101
 - Erlang Embedded Framework



Get in touch if you're interested.

Thank you

- <http://erlang-embedded.com>
- embedded@erlang-solutions.com
- @ErlangEmbedded

“ Any sufficiently complicated concurrent program in another language contains an ad-hoc, informally-specified, bug-ridden, slow implementation of half of Erlang.

– Robert Virding
Co-Inventor of Erlang

